Appendix to report:

SBJ-33-C5-OON-22-RE-013-APPD K12 - SHIP IMPACT, GLOBAL ASSESSMENT

Appendix title:

APPENDIX D - POST IMPACT EVALUATIONS

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D.1 Pontoon post impact evaluations

There has been performed considerations of the post impact properties of the pontoons. The given scenario is 8,5-13 m indentation between ship and pontoon, see Table 6-2, which theoretically could lead to water filling of four compartments.

The considerations done are simplified and conservative.

There has been considered three different impact scenarios for all three pontoons:

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Change in draft

The change in draft is iterated using the global model in Abaqus. When the changed buoyancy force in Abaqus (given as input) corresponds with the new draft (result of analysis) the new draft is found. The draft is as follows:

Bouyancy data	Pontoons high bridge	Pontoons ramp and anchors	Pontoons Iow bridge
Water plane area undamaged pontoon	924.0	795.9	665.1
Bouyancy force in Abaqus model	4.63E+07	3.70E+07	3.36E+07
	(pont 3)	(pont 12)	(pont 20)
Damage state 1			
Reduction factor bouyancy	0.60	0.60	0.61
Damaged water plane stiffness [N/m]	5.57E+06	4.83E+06	4.06E+06
Loss in bouyancy force same draft [N]	1.85E+07	1.47E+07	1.32E+07
U3 step-1 [m]	-0.08	0.04	0.00
U3 step damaged pontoon [m]	-1.38	-1.15	-1.15
Increased draft [m]	1.31	1.19	1.15
Extra bouyancy from increased draft [N]	7.13E+06	5.64E+06	4.58E+06
Updated loss of bouyancy [N]	1.14E+07	9.02E+06	8.59E+06

Post impact properties pontoons

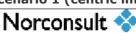
The three chosen scenarios give post-impact pontoon properties as shown below:

Pontoon property	Damage scenario	Pontoons high bridge	Pontoons ramp and anchors	Pontoons Iow bridge
Pontoon width [m]		17,0	14,5	12,0
Water plane vertical stiffness (heave [MN/m]), undamaged	9,3	8,0	6,7
Weak axis rotation (local roll), undan	naged [MNm/rad]	192,1	123,4	72,4
Strong axis rotation (local pitch), und	damaged [MNm/rad]	2351,6	2049,3	1734,8
Water plane vertical stiffness	Scenario 1	5,6	4,8	4.1
(heave), damaged [MN/m]	Scenario 2	7,0	6,0	5.1
	Scenario 3	7,1	6,1	5.1
Remaining water plane vertical	Scenario 1	60 %	60 %	61 %
stiffness (compared to undamaged state)	Scenario 2	75 %	75 %	75 %
	Scenario 3	76 %	76 %	76 %
Weak axis rotation stiffness (local	Scenario 1	115,2	74,5	44.0
roll), damaged state [MNm/rad]	Scenario 2	144,3	93,1	54.7
	Scenario 3	146,4	93,8	54.8
Strong axis rotation stiffness (local	Scenario 1	2162,7	1888,2	1601.5
pitch) [MNm/rad]	Scenario 2	1848,1	1619,9	1379.4
	Scenario 3	1331,8	1162,3	986.4
Remaining strong axis rotation	Scenario 1	92 %	92 %	92 %
stiffness (compared to undamaged state)	Scenario 2	79 %	79 %	80 %
	Scenario 3	57 %	57 %	57 %
Buoyancy eccentricity moment [MNm]	Scenario 1	79,2	66,2	54.5
	Scenario 2	207,4	173,6	142.7
	Scenario 3	292,7	250,0	209.7
Maximum theoretical local pitch rotation (overestimated) [deg]	Scenario 1	2,1	2,0	2.0
rotation (overestimated) [deg]	Scenario 2	6,4	6,2	6.1
	Scenario 3	12,6	12,5	12.5
Corresponding maximum static change in draft at pontoon ends	Scenario 1	1,1	1,0	1.0
(free-floating body - overestimated)	Scenario 2	3,2	3,2	3.1
+/- [m]	Scenario 3	6,4	6,3	6.3
Maximum static change in draft at po FE-model, see Appendix D section D.		1,8	1,6	1,3

Calculations of pontoon properties, pontoon axis 3, scenario 1 (centric impact):

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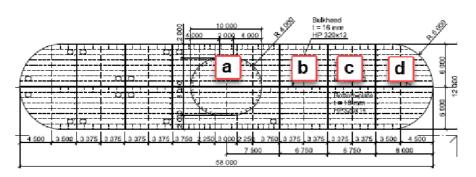


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Post impact evaluations pontoon properties (damaged)

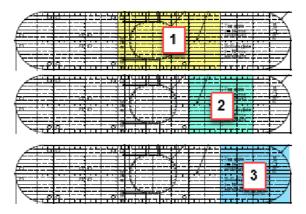
Geometry

K12-020 (120 m span, wamit 54, 55 and 56)



Given maximum intendation of 8.5 m at pontoon impact, there is a possibility of waterfilling of four compartments. This gives three possible combinations of waterfilled compartments:

Possible pontoon water fillings:



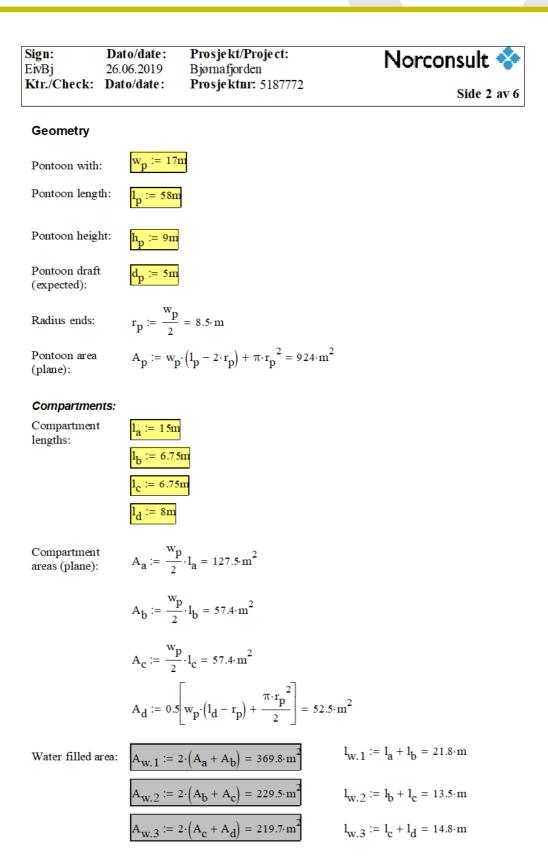
Chosen scenario:

comb := 1

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Damaged pontoon-properties 2019-06-20.xmcd

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Distance to center waterfilled area:

$$\begin{split} d_{w,1} &:= \frac{l_a + l_b}{2} - \frac{l_a}{2} = 3.4 \text{ m} \\ d_{w,2} &:= \frac{l_a}{2} + \frac{l_b + l_c}{2} = 14.3 \text{ m} \\ d_{w,3} &:= \frac{l_a}{2} + l_b + l_c = 21 \text{ m} \\ \end{split}$$
Bouyancy center:

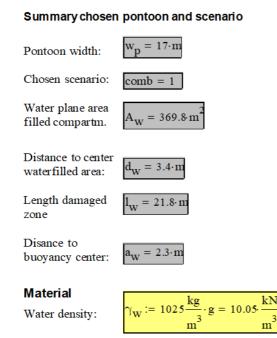
$$a_{w,1} &:= \frac{A_{w,1}}{A_p - A_{w,1}} \cdot d_{w,1} = 2.3 \text{ m} \qquad ; approximately \\ a_{w,2} &:= \frac{A_{w,2}}{A_p - A_{w,2}} \cdot d_{w,2} = 4.7 \text{ m} \\ a_{w,3} &:= \frac{A_{w,3}}{A_p - A_{w,3}} \cdot d_{w,3} = 6.6 \text{ m} \\ A_w &:= \begin{bmatrix} A_{w,1} & \text{if comb = 1} & = 369.8 \text{ m}^2 \\ A_{w,2} & \text{if comb = 2} \\ A_{w,3} & \text{if comb = 3} \\ a_{w,2} & \text{if comb = 3} \\ a_{w,2} & \text{if comb = 1} & = 2.3 \text{ m} \\ a_{w,2} & \text{if comb = 3} \\ a_{w,2} & \text{if comb = 3} \\ a_{w,2} & \text{if comb = 4} \\ a_{w,3} & \text{if comb = 3} \\ a_{w,3} & \text{if comb = 3} \\ a_{w,2} & \text{if comb = 3} \\ a_{w,3} & \text{if comb = 3} \\ a_{w,3} & \text{if comb = 3} \\ a_{w,2} & \text{if comb = 3} \\ a_{w,3} & \text{if comb = 3} \\ \end{bmatrix}$$

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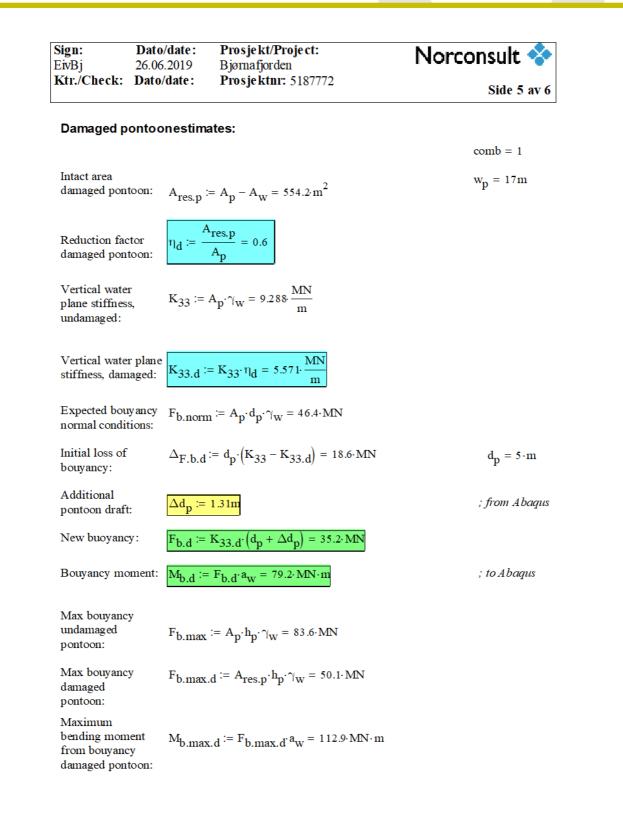
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m



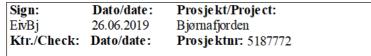
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Approximately water plane rotational stiffnesses:

Weak axis (local roll), undamaged:	$K_{44,p} := \gamma_{W} \frac{1}{12} \cdot w_{p}^{3} \cdot \left(l_{p} - 2\frac{2}{3}r_{p}\right) = 192.1 \cdot \frac{MN \cdot m}{rad}$
Weak axis (local roll), damaged:	$\mathbf{K}_{44.p.d} \coloneqq \eta_{\mathbf{d}} \cdot \mathbf{K}_{44.p} = 115.2 \cdot \frac{\mathbf{MN} \cdot \mathbf{m}}{\mathbf{rad}}$
Strong axis (local pitch), undamaged:	$\mathbf{K}_{55,p} \coloneqq \gamma_{\mathbf{W}} \cdot \left[\frac{1}{12} \cdot \mathbf{w}_{p} \cdot \left(\mathbf{l}_{p} \right)^{3} - 2 \left(2 \cdot \mathbf{r}_{p}^{2} - \frac{\pi \cdot \mathbf{r}_{p}^{2}}{2} \right) \cdot \left(\frac{\mathbf{l}_{p}}{2} - \frac{\mathbf{r}_{p}}{3} \right)^{2} \right]$
	$K_{55.p} = 2351.6 \frac{MN \cdot m}{rad}$
Strong axis (local pitch), damaged:	$\mathbf{K}_{55.p.d} \coloneqq \mathbf{K}_{55.p} - \gamma_{\mathbf{W}} \cdot \left(\frac{1}{12} \cdot \mathbf{w}_{p} \cdot \mathbf{l}_{\mathbf{W}}^{3} + \mathbf{A}_{\mathbf{W}} \cdot \mathbf{d}_{\mathbf{W}}^{2}\right) = 2162.7 \cdot \frac{\mathbf{MN} \cdot \mathbf{m}}{\mathbf{rad}}$
Remaining local pitch stiffness:	$\eta_{d.K55} \coloneqq \frac{K_{55.p.d}}{K_{55.p}} = 0.9$
Theoretical local pitch rotation:	$\varphi_{\mathbf{d}} := \frac{\mathbf{M}_{\mathbf{b},\mathbf{d}}}{\mathbf{K}_{55,\mathbf{p},\mathbf{d}}} = 2.1 \operatorname{deg}^{; too \ conservative \ as \ it \ does \ not \ take}_{into \ account \ the \ change \ in \ buoyancy}_{center \ due \ to \ local \ ptich \ rotation}$
Theoretical vertical displacement of pontoon end due to local pitch:	$U_{z.max.pontoon_end} := \varphi_d \cdot \frac{l_p}{2} = 1.1 \mathrm{m}$

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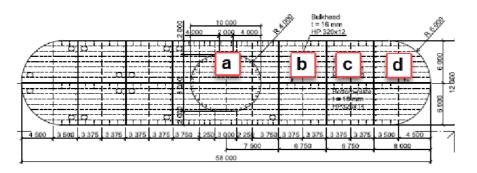
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Post impact evaluations pontoon properties (damaged)

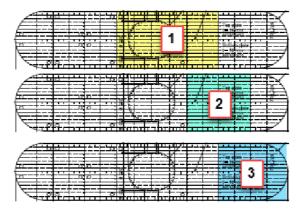
Geometry

K12-020 (120 m span, wamit 54, 55 and 56)



Given maximum intendation of 8.5 m at pontoon impact, there is a possibility of waterfilling of four compartments. This gives three possible combinations of waterfilled compartments:

Possible pontoon water fillings:



Chosen scenario:

comb := 3

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Geometry

:= 17m Pontoon with: Pontoon length: := 58m Pontoon height: := 9m Pontoon draft := 5m (expected): $r_p := \frac{w_p}{2} = 8.5 \cdot m$ Radius ends:

Pontoon area (plane):

$$\mathbf{A}_{\mathbf{p}} := \mathbf{w}_{\mathbf{p}} \cdot \left(\mathbf{l}_{\mathbf{p}} - 2 \cdot \mathbf{r}_{\mathbf{p}} \right) + \pi \cdot \mathbf{r}_{\mathbf{p}}^{2} = 924 \cdot \mathbf{m}^{2}$$

Compartments:

Compartment lengths:

$$l_a := 1.5m$$

 $l_b := 6.7.5m$
 $l_c := 6.7.5m$
 $l_d := 8m$

Compartment areas (plane):

$$A_a := \frac{w_p}{2} \cdot l_a = 127.5 \cdot m^2$$

$$\begin{aligned} \mathbf{A}_{\mathbf{b}} &:= \frac{\mathbf{w}_{\mathbf{p}}}{2} \cdot \mathbf{l}_{\mathbf{b}} = 57.4 \cdot \mathbf{m}^2 \\ \mathbf{A}_{\mathbf{c}} &:= \frac{\mathbf{w}_{\mathbf{p}}}{2} \cdot \mathbf{l}_{\mathbf{c}} = 57.4 \cdot \mathbf{m}^2 \\ \mathbf{A}_{\mathbf{d}} &:= 0.5 \left[\mathbf{w}_{\mathbf{p}} \cdot \left(\mathbf{l}_{\mathbf{d}} - \mathbf{r}_{\mathbf{p}} \right) + \frac{\pi \cdot \mathbf{r}_{\mathbf{p}}^2}{2} \right] = 52.5 \cdot \mathbf{m}^2 \end{aligned}$$

Water filled area:

$$l_{w.1} := 2 \cdot (A_a + A_b) = 369.8 \cdot m^2$$
$$l_{w.1} := l_a + l_b = 21.8 \cdot m$$
$$l_{w.2} := 2 \cdot (A_b + A_c) = 229.5 \cdot m^2$$
$$l_{w.2} := l_b + l_c = 13.5 \cdot m$$
$$l_{w.3} := 2 \cdot (A_c + A_d) = 219.7 \cdot m^2$$
$$l_{w.3} := l_c + l_d = 14.8 \cdot m$$

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Distance to center waterfilled area:

$$d_{w.1} := \frac{l_a + l_b}{2} - \frac{l_a}{2} = 3.4 \cdot m$$
$$d_{w.2} := \frac{l_a}{2} + \frac{l_b + l_c}{2} = 14.3 \cdot m$$
$$d_{w.3} := \frac{l_a}{2} + l_b + l_c = 21 \cdot m$$

 $a_{w.1} := \frac{A_{w.1}}{A_p - A_{w.1}} \cdot d_{w.1} = 2.3 \cdot m$

 $a_{w.2} := \frac{A_{w.2}}{A_p - A_{w.2}} \cdot d_{w.2} = 4.7 \cdot m$

; approximately

$$a_{w.3} := \frac{A_{w.3}}{A_p - A_{w.3}} \cdot d_{w.3} = 6.6 \cdot m$$

$$A_w := \begin{vmatrix} A_{w.1} & \text{if comb} = 1 \\ A_{w.2} & \text{if comb} = 2 \\ A_{w.3} & \text{if comb} = 3 \end{vmatrix}$$

$$a_w := \begin{vmatrix} a_{w.1} & \text{if comb} = 1 \\ a_{w.2} & \text{if comb} = 1 \\ a_{w.3} & \text{if comb} = 2 \\ a_{w.3} & \text{if comb} = 3 \end{vmatrix}$$

$$l_w := \begin{vmatrix} l_{w.1} & \text{if comb} = 1 \\ a_{w.3} & \text{if comb} = 3 \end{vmatrix}$$

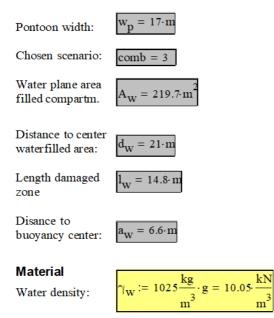
$$l_{w.2} & \text{if comb} = 2 \\ l_{w.3} & \text{if comb} = 3 \\ \end{vmatrix}$$

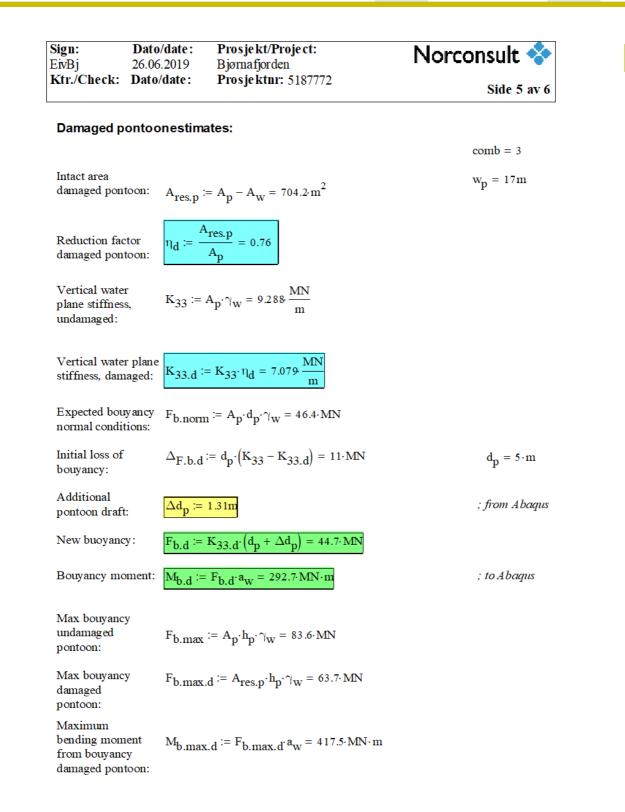
$$d_w := \begin{vmatrix} d_{w.1} & \text{if comb} = 1 \\ a_{w.3} & \text{if comb} = 3 \\ \end{vmatrix}$$

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 m^3

Summary chosen pontoon and scenario





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Weak axis (local roll), undamaged:	$\mathbf{K}_{44.p} := \gamma_{\mathbf{W}} \frac{1}{12} \cdot \mathbf{w}_{p}^{3} \cdot \left(\mathbf{l}_{p} - 2\frac{2}{3}\mathbf{r}_{p}\right) = 192.1 \cdot \frac{\mathbf{MN} \cdot \mathbf{m}}{\mathbf{rad}}$
Weak axis (local roll), damaged:	$\mathbf{K}_{44.p.d} \coloneqq \eta_{\mathbf{d}} \cdot \mathbf{K}_{44.p} = 146.4 \cdot \frac{\mathbf{MN} \cdot \mathbf{m}}{\mathbf{rad}}$
Strong axis (local pitch), undamaged:	$\mathbf{K}_{55.p} := \gamma_{\mathbf{W}} \cdot \left[\frac{1}{12} \cdot \mathbf{w}_{p} \cdot \left(\mathbf{l}_{p} \right)^{3} - 2 \left(2 \cdot \mathbf{r}_{p}^{2} - \frac{\pi \cdot \mathbf{r}_{p}^{2}}{2} \right) \cdot \left(\frac{\mathbf{l}_{p}}{2} - \frac{\mathbf{r}_{p}}{3} \right)^{2} \right]$
	$K_{55.p} = 2351.6 \frac{MN \cdot m}{rad}$
Strong axis (local pitch), damaged:	$K_{55.p.d} := K_{55.p} - \gamma_{w} \cdot \left(\frac{1}{12} \cdot w_{p} \cdot l_{w}^{3} + A_{w} \cdot d_{w}^{2}\right) = 1331.8 \cdot \frac{MN \cdot m}{rad}$
Remaining local pitch stiffness:	$\eta_{d.K55} \coloneqq \frac{K_{55.p.d}}{K_{55.p}} = 0.6$
Theoretical local pitch rotation:	$\varphi_{d} := \frac{M_{b,d}}{K_{55,p,d}} = 12.6 deg ; too conservative as it does not take into account the change in buoyancy center due to local ptich rotation$
Theoretical vertical displacement of pontoon end due to local pitch:	$U_{z.max.pontoon_end} := \varphi_d \cdot \frac{l_p}{2} = 6.4 \mathrm{m}$

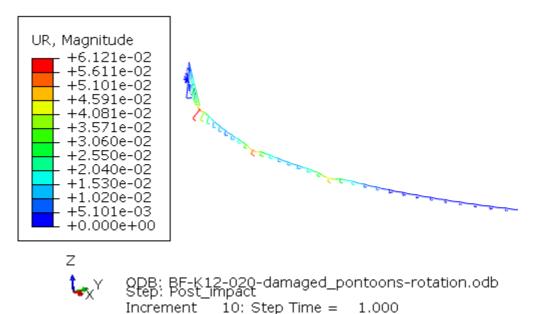
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C.1 Post-impact static state from FE-model

There has been performed a control of the permanent rotations in the damaged pontoons due to changed rotational water plane stiffness and the offset buoyancy center. Only scenario 3 has been evaluated as this is the extreme case. Updated water plane stiffnesses, buoyancy forces and -moments has been set on three pontoons on the global model: axis 3, 12 and 20.



This gives rotations of pontoon centers and corresponding drafts:

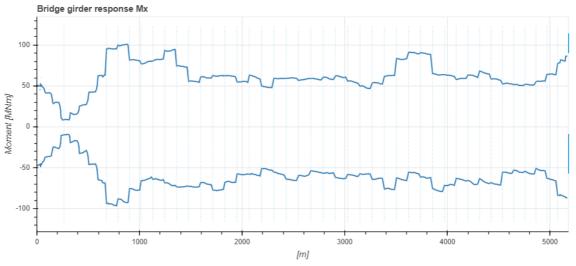
Rotation, center pontoon post impact	Pontoons	Pontoons ramp	Pontoons
(from abaqus)	high bridge	and anchors	low bridge
Local UR2 step 1 [rad]	0.00027571	0.000134135	0.00011709
Local UR2 post impact [rad]	0.061141	0.053413	0.0461207
Change in rotation [rad]	0.061	0.053	0.046
Change in rotation [deg]	3.5	3.1	2.6
Change in vertical displacement			
pontoon ends +/- [m]	1.77	1.55	1.33
Static draft pontoon center [m]	1.3	1.2	1.1
Maximum draft at damaged pontoon			
end [m]	3.1	2.7	2.5

Which are much lower than the same rotations when evaluating the pontoon alone as a freefloating body. The torsion stiffness of the girder and the interaction between the pontoons are significant.

Together with the static increased draft of 1,31 m (axis 3) the total vertical displacement of the damaged end of the axis 3 pontoon is (1,77+1,31=) 3,1 m. The freeboard is 4 m, but in a 100-years environmental case it must be expected green water on the pontoon deck and overtopping of waves. Both strong axis bending moment capacity of the columns and torsion capacity of the girder are very high and low utilized, so this is not considered critical for the bridge.

Strong axis bending moments for columns are shown in Appendix D section D.3 and are maximum 104 MNm, while the capacity is more than 1500 MNm (S420-steel).

Torsion moments in girder at 100-years environmental load from interactive, load combination 23 [MNm]:



The girder torsion moment capacity is at least 800 MNm (S420-steel) while max torsion moment at 100-years storm is approximately 100 MNm.



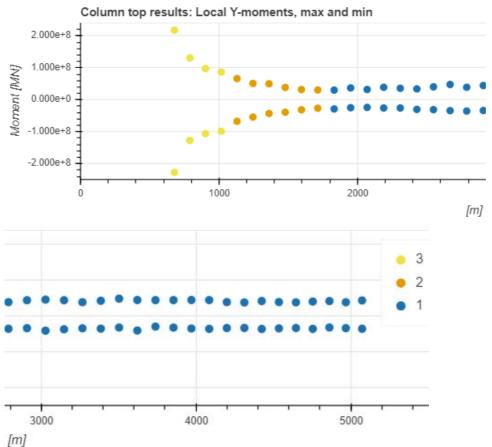
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C.2 Local damage in columns due to pontoon impact

Increased loads due to increased draft

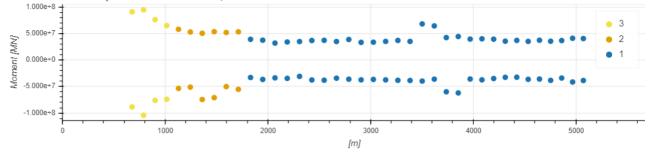
Increased pontoon draft leads to increased forces from current, sway and wind-generated waves. Column forces for the 100-years environmental loading is taken from load combination 23 on interactive, which is a SLS-state but with the same loads and load factors as the ALS-state with load factors of 1,0 on environmental loads and self-weight.

Section forces in column top, load combination 23 (SLS characteristic: 100-years conditions):



Weak axis bending moments in columns (max 227 MNm, axis 3) [Nm]:

Strong axis bending moment at column top (max 104 MNm, axis 4) [Nm]: Column top results: Local Z-moments, max and min



Increased loads due to plastic deformations of column top

The 90-degree impacts on axis 3 gives a plastic rotation of the column top, which gives a permanent displacement of 10 m of the pontoon center, see Appendix C part C.4.

Section forces in column due to increased draft

Load combination 23 - SLS 100 years (same as 100 years ALS)			
Section forces columns	Axis 3 (or 4 if larger)	Axis 12	Axis 20
Axial force col bottom (compression) [N]	3.34E+07	2.52E+07	2.52E+07
Weak axis bending moment col top [Nm]	2.27E+08	3.06E+07	4.78E+07
Strong axis bending moment col top [Nm]	1.04E+08	5.52E+07	3.50E+07
Torsion moment column [Nm]	5.34E+07	4.63E+07	4.18E+07
Estimated section forces 100-years storm post			
impact			
Permanent displacement of pontoon center due to			
yield in girder-column conection [m]	10	1	1
Increased pontoon draft [m]	1.31	1.19	1.15
Post impact environmental load scale factor (due to			
increased draft)	1.26	1.24	1.23
Axial force (same as for undamaged) [MN]	33.4	25.2	25.2
Extra bending from eccentricity [MNm]	334.0	25.2	25.2
Weak axis bending moment col top, incl scale factor			
[MNm]	286.9	37.8	58.8
Total weak axis bending moment [MNm]	620.9	63.0	84.0

The weak axis bending resistance is approximately 800 MNm, see pushover analysis in Appendix F. This means the column remains within the elastic area in the 100-years environmental loading.

As the weak axis second order moment from the buoyancy force is larger than the moment from environmental loads, the post-impact state is depending on the column design. If the weak axis capacity of the column is designed too low, the second order moment from the buoyancy could be higher than the moment resistance.

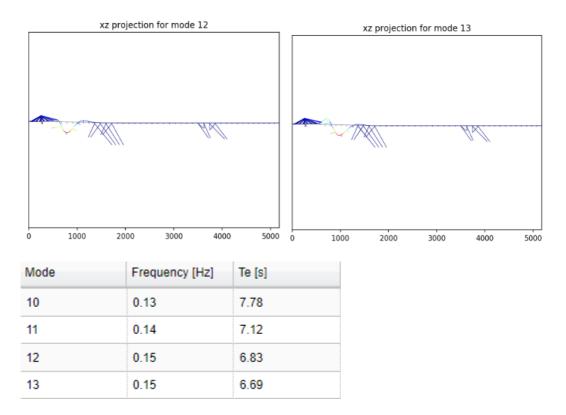




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C.3 Change in dynamic behavior due to increased mass in pontoon

The change of pontoon mass in the axis 3 pontoon due to filling of water will change the modal properties of the bridge. The modes 12 and 13 are pendulum modes where mainly the high bridge is participating. See plots from interactive and structural response analyses [1] in the figure below:



The pendulum modes are mainly trigged by the wind-sea, the sway gives little response on the bridge.

The wind sea is operation for periods lower than 5,5 second, see "Design basis MetOcean_rev_1", [2], while the pendulum modes have eigen periods above 7 seconds in an undamaged state. An increase of the time period for the pendulum modes will not lead to an increase in the loads due to dynamic effects, rather a decrease.

The bridge response is not expected to be affected by increased mass due to water filling of the pontoon.



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² 1 REFERENCES

- [1] SBJ-33-C5-OON-22-RE-012-B, «K12 Structural response analyses,» 2019.
- [2] Statens vegvesen, «SBJ-01-C4-SVV-01-BA-001 Design basis MetOcean_rev_1,» 2018.
- [3] SBJ-32-C5-OON-22-RE-003-B, «Analysis method,» 2019.
- [4] SBJ-33-C5-OON-22-RE-014-B, «K12 Ship impact, Pontoons and columns,» 2019.

