

Appendix K – Enclosure 8

10205546-13-NOT-194

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MEMO

PROJECT	Concept development, floating bridge E39 Bjørnafjorden	DOCUMENT CODE	10205546-13-NOT-194
CLIENT	Statens vegvesen	ACCESSIBILITY	Restricted
SUBJECT	Shear lag and buckling effects of Bridge Girder concept K12	PROJECT MANAGER	Svein Erik Jakobsen
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SUMMARY

When designing the bridge girder, effects of shear lag and plate buckling must be taken into account at the ultimate, serviceability and fatigue limit state. This memo presents the design requirements and the applied design approach accounting for these effects.

Sufficient capacity of the bridge girder subject to compression and biaxial bending is verified based on equation (4.15) in NS-EN 1993-1-5:2006 + NA 2009. Equation (4.15) is a linear summation of the utilization that each force component utilizes the capacity corresponding to the respective type of force. Due to the bridge girders shape with an inclined bottom plate, the capacity check will give conservative utilization results for biaxial bending when the utilization about each axis is large at the same time.

Since the Eurocode does not account for conservative utilizations due to geometric shapes, a second way of performing the capacity check has been introduced. In the second method, the geometric shape is considered in the capacity check by calculating the utilization at all the 7 extremity points of the girder based on the effective elastic section modulus for the specific point.

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1 Introduction

When designing the bridge girder, effects of shear lag and plate buckling must be taken into account at the ultimate, serviceability and fatigue limit state. This memo will present the design requirements and the applied design approach.

Calculation examples will be given, but the final results of the bridge girder capacity verification can be found in a closure to Appendix G: Global Analyses – Response, as it is a part of the post-processing routine of the global analyses results.

1.1 Design method

NS-EN 1993-1-5:2006 + NA:2009 provides two different design methods for plated steel structures; effective width method and reduced stress method. The applied method for the design of the bridge girder will be the effective width method, where all requirements are given in chapters 3 – 9 of the NS-EN 1993-1-5. The effective width method is efficient because it accounts for post-critical reserve in single plate elements and load shedding between cross-sectional elements.

Similar to the Eurocode, the following designation of three types of effective cross-section and effective width will be used in this memo:

- Effective^s includes effects of shear lag
- Effective^p includes effects of plate buckling
- Effective includes effects of both shear lag and plate buckling

1.2 Bridge girder

Figure 1 to Figure 3 shows the longitudinal steel in the typical bridge girder sections at mid span and by columns. Transverse bulkheads and trusses are not shown in the figures, as their design is not within the scope of this memo.

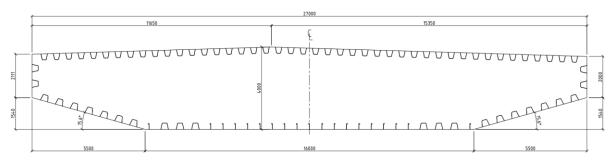


Figure 1 Bridge girder section at mid span

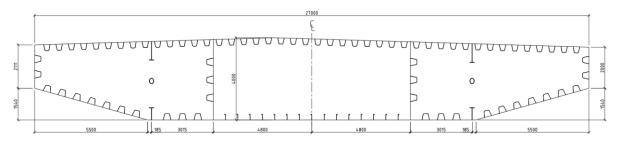


Figure 2 Bridge girder section by column axis 3 - 8

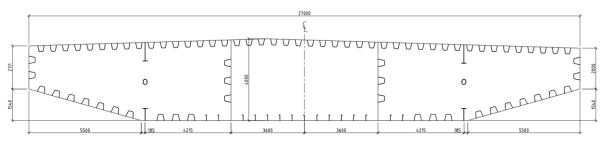


Figure 3 Bridge girder section by column axis 9 – 38

Figure 4 shows the positive direction of the v – vertical axis, h – horizontal axis and I – longitudinal axis as they are in the model for the global analysis of each bridge concept. The positive direction for the axial force, N_{Ed} , moment about the weak axis (horizontal), M_{weak} , and moment about the strong axis (vertical), M_{strong} , are also shown in the figure.

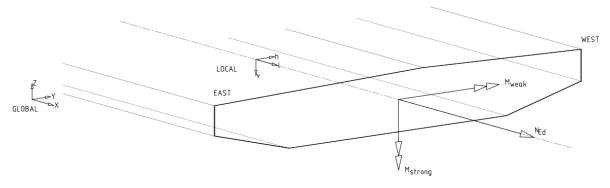


Figure 4 Local axis system in bridge girder and positive force direction

2 Design requirements

NS-EN 1993-1-5:2006 + NA:2009 (later referred to as EC3-5) gives design requirements of stiffened (and unstiffened) plates which are subject to in-plane forces.

2.1 Global analysis

According to clause 2.2(1)P in EC3-5, the effects of shear lag and of plate buckling on the stiffness of members shall be taken into account in the global analysis. Further on, in clause 2.2(5), it is stated that the effects of plate buckling on the stiffness can be ignored if the effective^p cross-sectional area of the girder in compression is larger than ρ_{lim} times the gross cross-sectional area of the girder. Clause NA.2.2(5) of the National Annex to EC3-5 gives the value of ρ_{lim} as 0.5.

2.2 Shear lag in member design

Shear lag effects are dependent on the span of the bridge, as well as the width of the internal elements in the flanges of the girder. With the typical span of Bjørnafjorden being 125 m, the distance L_e determined from Figure 3.1 in EC3-5 is 87,5 m for sagging bending, and 62,5 m for hogging bending.

According to clause 3.1(1) in EC3-5, the effects of shear lag may be neglected if half the width of the internal elements in the flanges of the girder is less than $L_e/50$. This is never the case for the bridge girder of Bjørnafjorden, hence shear lag effects should be considered at serviceability and fatigue limit state according to clause 3.2.1, and at ultimate limit state according to clause 3.3 of EC3-5.

2.3 Plate buckling effects due to direct stresses at the ultimate limit state

Sufficient capacity of the bridge girder due to direct stresses is verified based on equation (4.15) given in clause 4.6(1) in EC3-5:

$$\eta_{1} = \frac{N_{Ed}}{\frac{f_{y}A_{eff}}{\gamma_{M0}}} + \frac{M_{y,Ed} + N_{Ed}e_{y,N}}{\frac{f_{y}W_{y,eff}}{\gamma_{M0}}} + \frac{M_{z,Ed} + N_{Ed}e_{z,N}}{\frac{f_{y}W_{z,eff}}{\gamma_{M0}}} \quad (4.15)$$

The effective cross-sectional properties of the girder are based on the effective areas of the compression elements and on the effective^s area of the tension elements due to shear lag, in accordance with clause 4.3(2).

According to clause 4.3(3) and 4.3.(4), the effective^p area A_{eff} should be determined assuming that the cross-section is subject only to stresses due to uniform axial compression. The shift, $e_{y,N}$ and $e_{z,N}$, of the centroid of the effective^p area A_{eff} relative to the center of gravity of the gross cross-section, gives and additional moment which should be taken into account in the cross-section verification. The effective section modulus W_{eff} should be determined assuming the cross-section is subject only to bending stresses about the respective axis.

2.4 Further requirements

In addition to the requirements for checking effects of shear lag and plate buckling effects due to direct stresses, NS-EN 1993-1-5:2006 + NA:2009 also gives requirements and resistance models for shear buckling and buckling due to transverse loads.

Experience show that buckling effects due to shear loads for a heavily stiffened plated structure are very low (often neglectable), thus at this stage of design, the shear resistance is considered as full. A check of the von mises stress in the girder at ULS is performed in order to verify the capacity. Results of this check can be found in a closure to 90-RE-107 Appendix G: Global Analyses – Response_0

3 Shear lag effects

At serviceability and fatigue limit state, an effective^s width for elastic shear lag is used in accordance with clause 3.2 of EC3-5. The effective^s width is $b_{eff} = \beta b_0$, where the effective^s width factor β is calculated based on formulas given in table 3.1 of the Eurocode.

In the global analysis, the stiffness of the bridge girder about the weak axis is based on the effective^s cross-section attained by using the effective^s flange widths $b_{eff} = \beta b_{0.}$

Refer to memo 13-NOT-099 – FEM analysis of bridge girder and column for verification of shear lag factors calculated according to clause 3.2 of the Eurocode compared to the shear lag experienced in the local FE-model of the bridge girder.

At ultimate limit state, elastic-plastic shear lag effects are taken into account as given in clause 3.3(1)c). As the National Annex does not specify a preferred method, the recommended method in NOTE 3 is adapted. The effective^s width is $b_{eff} = \beta^{\kappa} b_0$, where the factors β and κ are calculated according to table 3.1 of NS-EN 1993-1-5.

The elastic-plastic shear lag effects are combined with the effects of plate buckling due to direct stresses at the ultimate limit state. This is further explained in section 4.2.4 of this memo.

An additional check of the von mises stresses at 7 extremity points of the bridge girder is performed at the ultimate limit state. For these calculations, the effective^s flange width applied when calculating the second moment of area about the weak axis is taken as $b_{eff} = b_0 \beta^{\kappa}$.

3.1 Calculation example

On the following pages, examples of calculations of β and β^{κ} factors at sagging and hogging bending are shown.

Figure 5 shows the girder section at sagging bending. Top and bottom flanges are internal flanges, and the width b_0 is half of their width. The calculations below give the β and β^{κ} for the top and the bottom flange.

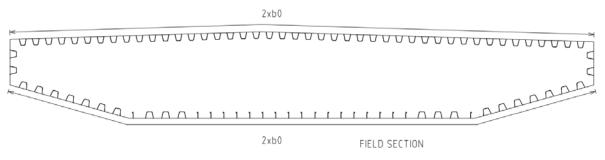
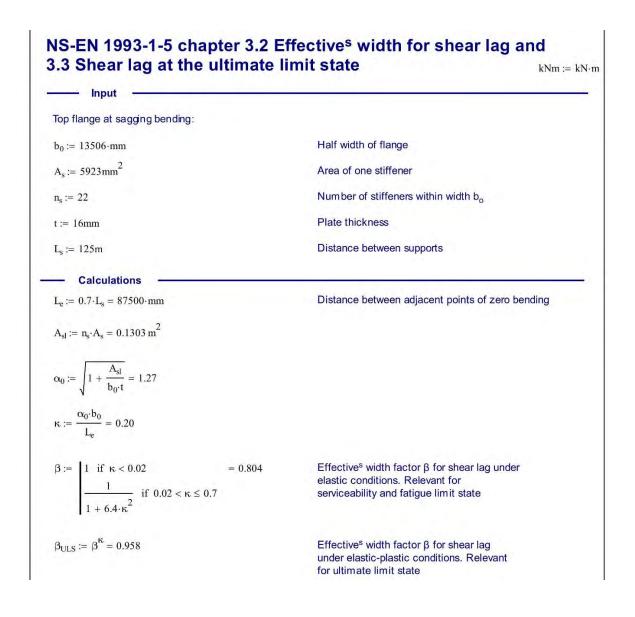


Figure 5 Section at sagging bending



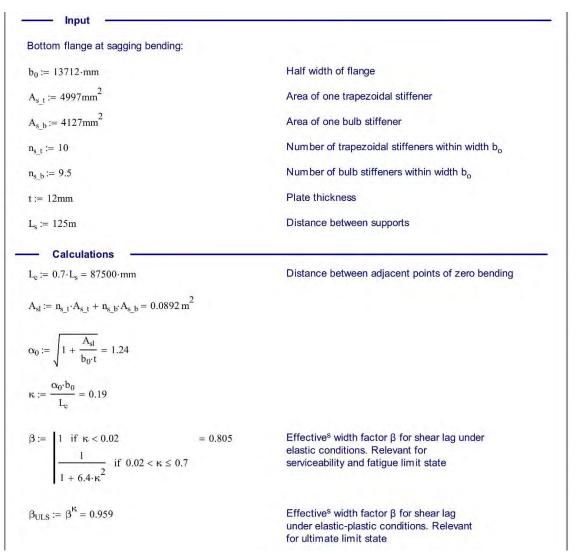
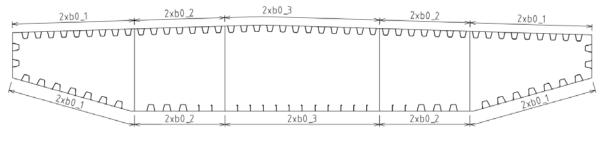
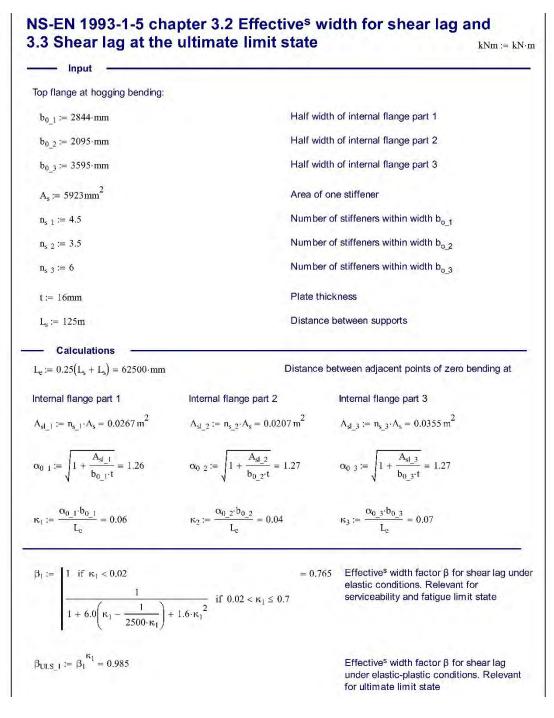


Figure 6 shows the girder section at hogging bending. The flanges are supported by longitudinal girders, causing each flange to be separated into five widths where each width b_0 is half of the internal widths. Due to symmetry, some widths are identical. The calculations below give the β and β^{κ} factors for the top flange only.



SUPPORT SECTION

Figure 6 Section at hogging bending



$$\beta_{2} := \begin{vmatrix} 1 & \text{if } \kappa_{2} < 0.02 \\ \hline 1 \\ \hline 1 + 6.0 \left(\kappa_{2} - \frac{1}{2500 \cdot \kappa_{2}} \right) + 1.6 \cdot \kappa_{2}^{-2} \\ \text{if } 0.02 < \kappa_{2} \le 0.7 \end{vmatrix} = 0.832 \qquad \begin{array}{l} \text{Effective}^{\text{s}} \text{ width factor } \beta \text{ for shear lag under elastic conditions. Relevant for serviceability and fatigue limit state} \\ \beta_{\text{ULS } 2} := \beta_{2}^{-\kappa_{2}} = 0.992 \\ \beta_{3} := \begin{vmatrix} 1 & \text{if } \kappa_{3} < 0.02 \\ \hline 1 + 6.0 \left(\kappa_{3} - \frac{1}{2500 \cdot \kappa_{3}} \right) + 1.6 \cdot \kappa_{3}^{-2} \\ \text{if } 0.02 < \kappa_{3} \le 0.7 \end{aligned} = 0.707 \qquad \begin{array}{l} \text{Effective}^{\text{s}} \text{ width factor } \beta \text{ for shear lag under elastic conditions. Relevant for serviceability and fatigue limit state} \\ \beta_{0\text{ULS } 3} := \beta_{3}^{-\kappa_{3}} = 0.975 \end{aligned}$$

$$\begin{array}{l} \text{Effective}^{\text{s}} \text{ width factor } \beta \text{ for shear lag under elastic conditions. Relevant for serviceability and fatigue limit state} \\ \text{Effective}^{\text{s}} \text{ width factor } \beta \text{ for shear lag under elastic conditions. Relevant for serviceability and fatigue limit state} \\ \beta_{0\text{ULS } 3} := \beta_{3}^{-\kappa_{3}} = 0.975 \end{aligned}$$

3.2 Summary of shear lag factors for all cross-sections

CONCE	EPT K12								Elastic (SLS, FLS)		Elsatic-plastic (ULS)	
Span	125m	b₀ top	b ₀ bot	Le	кtop	κbot	a₀ top	a₀ bot	βtop	βbot	βtop	βbot
Cross-s	section	[m]	[m]	[m]	[-]	[-]	[-]	[-]	[-]	[-]	[-]	[-]
Field (I	F1_rev05)	13,51	13,71	87,50	0,20	0,19	1,27	1,24	0,80	0,80	0,96	0,96
Field (I	F2_rev00)	13,51	13,71	87,50	0,20	0,19	1,27	1,21	0,80	0,81	0,96	0,96
Transit	tion (T1_rev00) ·	– saggin	g bending	-								
	Section b0_1	4,95	5,05	87,50	0,07	0,07	1,27	1,21	0,97	0,97	1,00	1,00
	Section b0_2	3,60	3,60	87,50	0,05	0,05	1,27	1,23	0,98	0,98	1,00	1,00
	Section b0_3	4,95	5,05	87,50	0,07	0,07	1,27	1,21	0,97	0,97	1,00	1,00
Transit	tion (T1_rev00)	– hoggir	g bendin	g								
	Section b0_1	4,95	5,05	62,50	0,10	0,10	1,27	1,21	0,63	0,63	0,95	0,96
	Section b0_2	3,60	3,60	62,50	0,07	0,07	1,27	1,23	0,71	0,71	0,97	0,98
	Section b0_3	4,95	5 <i>,</i> 05	62,50	0,10	0,10	1,27	1,21	0,63	0,63	0,95	0,96
Transit	tion (T1_rev00)	– Linear	interpola	tion be	tween	sagging	bending	g and ho	gging be	nding		
	Section b0_1	4,95	5,05						0,80	0,80	0,98	0,98
	Section b0_2	3,60	3,60						0,84	0,85	0,99	0,99
	Section b0_3	4,95	5 <i>,</i> 05						0,80	0,80	0,98	0,98
Suppo	rt (S1_rev02)											
	Section b0_1	2,84	2,95	62,50	0,06	0,06	1,27	1,18	0,77	0,77	0,99	0,99
	Section b0_2	2,10	2,10	62,50	0,04	0,04	1,27	1,17	0,83	0,85	0,99	0,99
	Section b0_3	3,59	3,60	62,50	0,07	0,07	1,27	1,19	0,71	0,73	0,98	0,98
	Section b0_4	2,10	2,10	62,50	0,04	0,04	1,27	1,17	0,83	0,85	0,99	0,99
	Section b0_5	2,84	2,95	62,50	0,06	0,06	1,27	1,18	0,77	0,77	0,98	0,99
Suppo	rt (S2_rev00)											

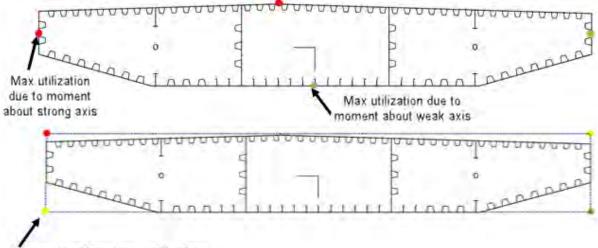
Section b0_1	2,84	2,95	62,50	0,06	0,06	1,27	1,19	0,76	0,77	0,98	0,99
Section b0_2	2,10	2,10	62,50	0,04	0,04	1,27	1,17	0,83	0,85	0,99	0,99
Section b0_3	3,59	3,60	62,50	0,07	0,07	1,27	1,17	0,71	0,73	0,97	0,98
Section b0_4	2,10	2,10	62,50	0,04	0,04	1,27	1,17	0,83	0,85	0,99	0,99
Section b0_5	2,84	2,95	62,50	0,06	0,06	1,27	1,19	0,76	0,77	0,98	0,99

Shear lag and buckling effects of Bridge Girder

4 Plate buckling effects

The bridge girder is a member in cross-section class 4, meaning local buckling will occur before the attainment of yield stress in one or more parts of the cross-section.

Sufficient capacity of the bridge girder subject to compression and biaxial bending is verified based on equation (4.15) in NS-EN 1993-1-5:2006 + NA 2009. Equation (4.15) is a linear summation of the utilization that each force component utilizes the capacity corresponding to the respective type of force. Due to the bridge girders geometric shape with an inclined bottom plate, the summation of the utilization will give conservative utilization results for biaxial bending when the utilization about each axis is large at the same time, see Figure 7.



Summation of maximum utilizations

Figure 7 Illustration of the capacity check combining maximum utilizations of the moment about each axis

Since the Eurocode does not account for conservative utilizations due to geometric shapes, a second way of performing the capacity check has been introduced. This second method is denoted method 2 in the results given in a closure to 90-RE-107 Appendix G: Global Analyses – Response_0, while the method described above is denoted method 1.

For method 2, the utilization at all the 7 extremity points of the girder is calculated based on the effective elastic section modulus for the specific point.

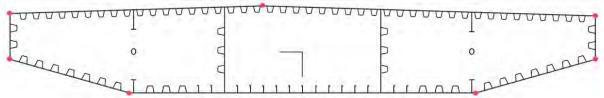


Figure 8 The 7 extremity points of the bridge girder controlled with method 2 of the capacity check

As shown in section 5 of this memo, the effective^p cross-sectional area of the girder in compression is always larger than 0.5 times the gross cross-sectional area, hence plate buckling effects on the stiffness is ignored in the global analysis in accordance with clause 2.2(5) in EC3-5.

4.1 Break-down of eqution 4.15 of EC3-5

A modified version of equation (4.15) is shown below. The equation is modified to adapt to the axis notation and force direction of this project.

$$\eta_{1} = -\frac{N_{Ed}}{\frac{f_{y}A_{eff}}{\gamma_{M0}}} + \frac{M_{weak,Ed} + N_{Ed}e_{w,N}}{\frac{f_{y}W_{weak,eff}}{\gamma_{M0}}} + \frac{M_{strong,Ed} + N_{Ed}e_{s,N}}{\frac{f_{y}W_{strong,eff}}{\gamma_{M0}}} \quad modified (4.15)$$

Where

A_{eff} is

- $A_{eff,c}$ effective^p cross-section area when N_{Ed} is axial compression
- A_{eff,t} gross cross-section area when N_{Ed} is axial tension

$e_{w,N}\,and\,e_{s,N}\,is$

- $e_{w,N,c}$ eccentricity of the neutral axis in vertical direction when N_{Ed} is axial compression. Gives an additional moment about the weak axis.
- e_{w,N,t} zero when N_{Ed} is axial tension. No eccentricity moment
- e_{s,N,c} eccentricity of the neutral axis in horizontal direction when N_{Ed} is axial compression.
 Gives an additional moment about the strong axis.
- e_{s,N,t} zero when N_{Ed} is axial tension. No eccentricity moment

For method 1 of the capacity check, the equation is applied one time for the entire girder. Where $W_{weak,eff}$ is

- W⁺_{weak,eff} effective elastic section modulus for a positive moment about the weak axis
- W⁻weak,eff effective elastic section modulus for a negative moment about the weak axis

W_{strong,eff} is

- W⁺_{strong,eff} effective^p elastic section modulus for a positive moment about the strong axis
- W⁻_{strong,eff} effective^p elastic section modulus for a negative moment about the strong axis

For method 2 of the capacity check, the equation is applied for the 7 extremity points of the girder. Where

 $W_{\mathsf{weak},\mathsf{eff}} \, is$

- W⁺_{weak,eff} effective elastic section modulus for each specific point on the girder for a positive moment about the weak axis
- W⁻_{weak,eff} effective elastic section modulus for each specific point on the girder for a negative moment about the weak axis

W_{strong,eff} is

- W⁺_{strong,eff} – effective^p elastic section modulus for each specific point on the girder for a positive moment about the strong axis

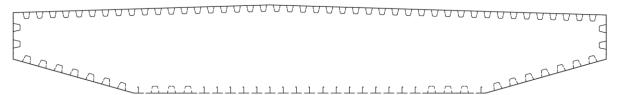
- W⁻_{strong,eff} – effective^p elastic section modulus for each specific point on the girder for a negative moment about the strong axis

4.2 Effective cross-sections

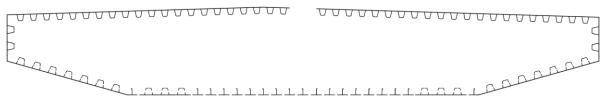
As explained above, verification with equation (4.15) requires cross-sectional data for six different effective cross-sections depending on the direction of N_{Ed} , $M_{weak,Ed}$ and $M_{strong,Ed}$:

1. Gross cross-section for N_{ed} as a tensional force, ie. the whole cross-section is in the tension zone and there are no bucklings effects due to this force component

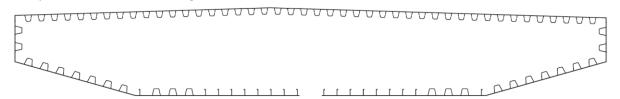
2. Effective^p cross-section for N_{ed} as a compressional force, ie. the whole cross-section is in the compression zone.



3. Effective cross-section for M_{weak,Ed} as a positive moment about the horizontal axis, ie. all parts below the horizontal neutral axis is in the compression zone. Shear lag effects of the compression and tension flange are included.



4. Effective cross-section for M_{weak,Ed} as a negative moment about the horizontal axis, ie. all parts above the horizontal neutral axis is in the compression zone. Shear lag effects of the compression and tension flange are included.



- 5. Effective^p cross-section for M_{strong,Ed} as a positive moment about the vertical axis, ie. all parts east of the vertical neutral axis is in the compression zone.
- 6. Effective^p cross-section for M_{strong,Ed} as a negative moment about the vertical axis, ie. all parts west of the vertical neural axis is in the compression zone.



Due to symmetry, the effective^p cross-sections for $M_{strong,Ed}$ as a positive moment is the mirrored of the effective^p cross-sections for $M_{strong,Ed}$ as a negative moment.

The effective^p area of the compression zone in each of the effective^p cross-sections is the effective^p area of each stiffener and the effective^p part of the panel between the stiffeners. Both local buckling of each plate element and global buckling of the stiffened panel is accounted for.

The reduction factors, ρ_{loc} and ρ_{c} , due to plate buckling is calculated as explained in the following sections.

4.2.1 Local plate buckling effects

The reduction factor ρ_{loc} for all subpanels in cross-section class 4 in the compression zone is calculated according to clause 4.4(2) of EC3-5. The stress distribution within all internal compression elements are conservatively set to constant. This gives a buckling factor k_{σ} of 4.0 for all elements, and the effective width of the internal element is distributed with half of the effective width to each side of the element, see Figure 9.

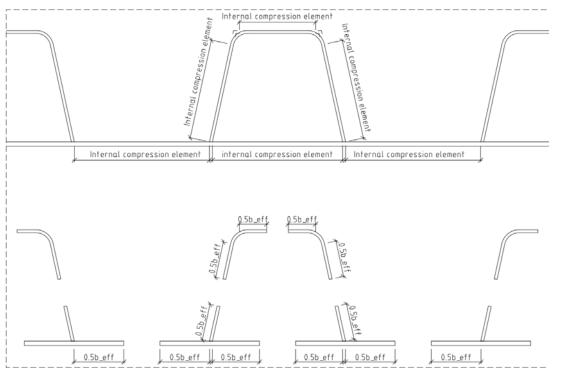
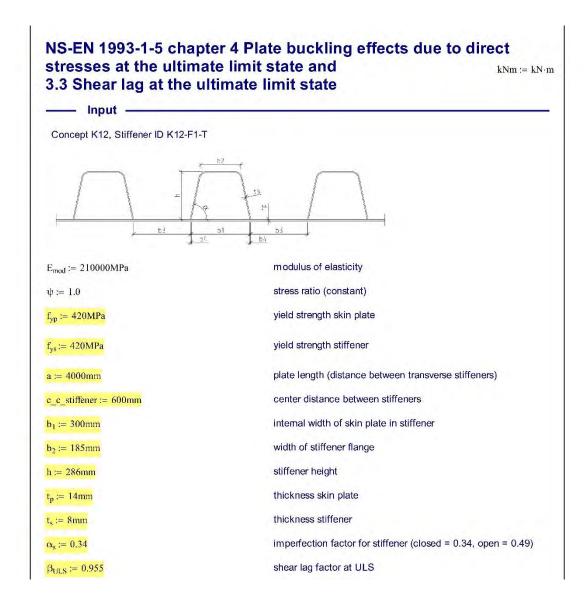


Figure 9 Illustration of effective^p widths due to local buckling of internal compression elements

Calculation example of local buckling effects



Local buckling of internal plate elements according to NS-EN 1993-1-5 4.5.1(4) Internal width of skin plate in stiffener, b1 $class_{b1} := \begin{bmatrix} "1-3" & if \frac{b_1}{t_p} \le 42 \cdot \varepsilon_p & = "1-3" \\ "4" & otherwise \end{bmatrix}$ class buckling factor 4 otherwise $\lambda_{b1} :=$ "no local buckling" if $k_{\sigma b1}$ = "no local buckling" = "no local buckling" slendemess $\frac{\frac{b_1}{t_p}}{28.4 \cdot \varepsilon_p \cdot \sqrt{k_{\sigma p_1}}} \quad \text{otherwise}$
$$\begin{split} \rho_{b1} &\coloneqq \left[\begin{array}{ll} 1 \quad \text{if } \left(\lambda_{b1} = \text{"no local buckling"} \right) \vee \lambda_{b1} \leq 0.5 + \sqrt{0.085 - 0.055 \cdot \psi} &= 1.000 \\ \min \Biggl[1, \frac{\lambda_{b1} - 0.055 \cdot (3 + \psi)}{\lambda_{b1}^2} \Biggr] & \text{otherwise} \end{split} \right] \end{split}$$
reduction factor $b_{eff\ b1} := b_1 \cdot p_{b1} = 300 \cdot mm$ effective width Stiffener flange, b2 $class_{b2} := \left| \begin{array}{cc} "1\text{-}3" & \text{if} \ \frac{b_2}{\iota_s} \leq 42 \cdot \varepsilon_s & = "1\text{-}3" \\ "4" & \text{otherwise} \end{array} \right|$ class $k_{\sigma b2} :=$ "no local buckling" if $class_{b2} = "1-3" =$ "no local buckling" buckling factor 4 otherwise $\begin{array}{ll} \lambda_{b2} \coloneqq & \begin{array}{ll} \text{"no local buckling"} & \text{if } k_{\sigma b2} = \text{"no local buckling"} & = \text{"no local buckling"} \\ & \\ \hline \frac{b_2}{t_s} \\ \hline 28.4 \cdot \varepsilon_{s'} \sqrt{k_{\sigma b2}} \end{array} & \text{otherwise} \end{array}$ slendemess
$$\begin{split} \rho_{b2} &\coloneqq \quad \left| \begin{array}{l} 1 \quad \text{if } \left(\lambda_{b2} = \text{"no local buckling"} \right) \vee \lambda_{b2} \leq 0.5 + \sqrt{0.085 - 0.055 \cdot \psi} &= 1.000 \\ \\ \min \Biggl[1, \frac{\lambda_{b2} - 0.055 \cdot (3 + \psi)}{\lambda_{b2}^2} \Biggr] & \text{otherwise} \end{split} \right. \end{split}$$
reduction factor effective width $b_{eff b2} := b_2 \cdot \rho_{b2} = 185 \cdot mm$

Width of skin plate between stiffeners, b3 $class_{b3} := \left| \begin{array}{c} "1\text{-}3" & \text{if } \frac{b_3}{t_p} \leq 42 \cdot \varepsilon_p & = "1\text{-}3" \end{array} \right|$ class $k_{\sigma b3} :=$ "no local buckling" if $class_{b3} = "1-3" =$ "no local buckling" buckling factor 4 otherwise $\lambda_{b3} \coloneqq \quad \text{"no local buckling"} \quad \text{if } k_{\sigma b3} \text{ = "no local buckling"} \quad \text{= "no local buckling"}$ slenderness $\frac{\frac{b_3}{t_p}}{28.4 \cdot \varepsilon_n \cdot \sqrt{k_{rrb3}}} \text{ otherwise}$ $\rho_{b3} \coloneqq \left[1 \text{ if } \left(\lambda_{b3} = \text{"no local buckling"} \right) \vee \lambda_{b3} \le 0.5 + \sqrt{0.085 - 0.055 \cdot \psi} \right] = 1.000$ reduction factor $\left|\min\left[1,\frac{\lambda_{b3}-0.055\cdot(3+\psi)}{\lambda_{b3}^{2}}\right] \text{ otherwise }\right|$ effective width $b_{eff\ b3}\coloneqq b_{3^*}\rho_{b3}=284{\cdot}mm$ Inclined stiffener web, bs class_{bs} := $\begin{vmatrix} "1 - 3" & \text{if } \frac{b_s}{t_s} \le 42 \cdot \varepsilon_s \\ "4" & \text{otherwise} \end{vmatrix}$ class $k_{\sigma bs}$:= "no local buckling" if $class_{bs}$ = "1-3" = 4 4 otherwise buckling factor $\lambda_{bs} := \begin{vmatrix} \text{"no local buckling"} & \text{if } k_{\sigma bs} = \text{"no local buckling"} &= 0.85 \\ \\ \frac{\frac{b_s}{t_s}}{28.4 \cdot \epsilon_{s'} \sqrt{k_{mb}}} & \text{otherwise} \end{vmatrix}$ slenderness
$$\begin{split} \rho_{bs} &\coloneqq \left[\begin{array}{c} 1 \quad \text{if } \left(\lambda_{bs} = \text{"no local buckling"} \right) \vee \lambda_{bs} \leq 0.5 + \sqrt{0.085 - 0.055 \cdot \psi} &= 0.873 \\ \min \left[1, \frac{\lambda_{bs} - 0.055 \cdot (3 + \psi)}{\lambda_{bs}^2} \right] & \text{otherwise} \\ \end{split} \right] \end{split}$$
reduction factor effective width $b_{eff\ bs}\coloneqq b_s{\cdot}\rho_{bs}=252{\cdot}mm$ Effective^ploc area after reduction due to local plate buckling $A_{st_cff_loc} := t_s \cdot (2 \cdot b_{cff_bs} + b_{cff_b2}) = 5509 \text{ mm}^2$ effectivePloc area of stiffener $A_{p_eff_loc} := t_p \cdot \left(2 \cdot b_4 + b_{eff_b1} + b_{eff_b3}\right) = 8400 \text{ mm}^2$ effectiveploc area of skin plate $A_{sl \ 1} \ eff \ loc} := A_{st \ eff \ loc} + A_{p \ eff \ loc} = 13909 \ mm^2$ effectiveploc area of stiffened plate

4.2.2 Global plate buckling effects

Plate type behavior

Since all plates of the bridge girder are heavily stiffened, the plate type buckling behavior is ignored because the column type behavior will prevail.

Column type buckling behavior

The global reduction factor ρ_c due to column type buckling behavior of a stiffener and the adjacent part of panel between the stiffeners is calculated in accordance with section 4.5.3 of EC3-5.

Clause 4.5.3(3) states that the elastic critical column buckling stress $\sigma_{cr,c}$ may be determined from the elastic critical column buckling stress $\sigma_{cr,sl}$ of the stiffener closest to the panel edge with the highest compressive stress.

Due to different types of stiffeners, trapezoidal and bulbs, in the bottom plate, the reduction factor ρ_c is calculated separately for each type of stiffener based on their respective elastic critical column buckling stress $\sigma_{cr,sl}$.

Example calculation of global buckling effects (continuation of example for local buckling effects)

$$\begin{array}{l} \label{eq:Global column type buckling according to NS-EN 1993-1-5 4.5.3} \\ \beta_{Ae} := \displaystyle \frac{A_{sl_1} \cdot \operatorname{off} \cdot \operatorname{loc}}{A_{sl_1}} = 0.96 & \operatorname{correction factor for column slenderness} \\ \\ \sigma_{cr.e} := \displaystyle \frac{\pi^2 \cdot E_{mod} \cdot I_{sl_1}}{A_{sl_1} \cdot a^2} = 1521 \cdot \mathrm{MPa} & \operatorname{elastic critical column buckling stress} \\ \\ \lambda_e := \displaystyle \sqrt{\frac{\beta_{Ae} \cdot f_{yy}}{\sigma_{er.e}}} = 0.51 & \operatorname{relative column slenderness} \\ \\ \sigma_{s_e} := \displaystyle \alpha_s + \displaystyle \frac{0.09}{\frac{i}{\max(e_1, e_2)}} = 0.43 & \operatorname{modified imperfection factor NS-EN 1993-1-5 eq. 4.12} \\ \\ \Phi_e := \displaystyle 0.5 \cdot \left[1 + \displaystyle \alpha_{s_e} \cdot (\lambda_e - 0.2) + \displaystyle \lambda_e^2\right] = 0.70 & \operatorname{function used to calculate column type buckling reduction factor } \\ \\ \rho_e := \displaystyle \frac{1}{\Phi_e + \displaystyle \sqrt{\Phi_e^2 - \lambda_e^2}} = 0.852 & \operatorname{global reduction factor due to column type buckling} \end{array}$$

4.2.3 Combined local and global plate buckling effects

In accordance with clause 4.5.1(3), the final effective^p area of the compression zone in the bridge girder is the effective^p area reduced due to local buckling times the reduction factor due to global buckling, except the effective^p parts of skin plate which is supported by an adjacent plate, which is not to be reduced due to global buckling effects:

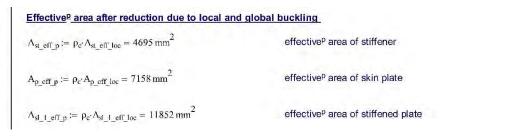
 $A_{c,eff} = \rho_c A_{c,eff,loc} + \Sigma b_{edge,eff} t$

As mentioned, the global reduction factor ρ_c will differ depending on the type of stiffener, hence the equation above may be rewritten as

 $A_{c,eff} = \Sigma \rho_{c,sl} A_{sl,eff,loc} + \Sigma b_{edge,eff} t$

Where $A_{sl,eff,loc}$ is the effective^p area of a stiffener and the adjacent part of panel reduced for local buckling, and $\rho_{c,sl}$ is the global reduction factor corresponding to the same type of stiffener.

When calculating the geometric properties A_{eff} and W_{eff} for the effective^p girder composed of different plates, the global reduction factor $\rho_{c,sl}$ is taken into account by reducing the thickness of the skin plate and the thickness of the stiffeners.



4.2.4 Combined shear lag and plate buckling effects

The elastic-plastic shear lag effects are combined with the effects of plate buckling due to direct stresses at the ultimate limit state according to equation (3.5) of EC3-5:

 $A_{eff} = A_{c,eff} \beta^{\kappa}$

Where $A_{c,eff}$ is the effective^p area of the compression flange. For the tension flange, the effective width $b_{eff} = b_0 \beta^{\kappa}$ is adapted.

When calculating the geometric property W_{eff} for the effective girder, the shear lag reduction factor β^{κ} is taken into account by reducing the thickness of the skin plate and the thickness of the stiffeners in the compression flange.

Combined shear lag and buckling eff	fects
Effective area after reduction due to shear lag	and buckling effects
$A_{st_off} := \beta_{ULS} \cdot A_{st_off_p} = 4483 \text{ mm}^2$	effective area of stiffener
$A_{p_elT} \coloneqq \beta_{ULS} \cdot A_{p_elT_p} = 6836 \text{mm}^2$	effective area of skin plate
$A_{sl_1_off} := \beta_{ULS} \cdot A_{sl_1_off_p} = 11319 \text{mm}^2$	effective area of stiffened plate

5 Cross-section data

On the following pages, cross-sectional data of the typical bridge girder sections at mid span and by columns are given:

